

$$\sum F_x = 20 - \frac{1}{2}(15) - F \cos \theta = 0$$

$$\sum F_y = \frac{\sqrt{3}}{2}(15) - F \sin \theta = 0$$

$$\tan \theta = 1.039 \rightarrow \theta = 46.10^\circ$$

$$F = 18.03 \text{ N}$$

2. $\vec{r}_{A/B} = (2, 2, 1)$; $|\vec{r}_{A/B}| = 3$

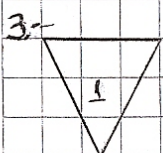
a) $\vec{F} = 4\hat{i} + 4\hat{j} + 2\hat{k} \text{ N}$

b) $\vec{M}_O = -10\hat{i} + 2\hat{j} + 16\hat{k} \text{ N}\cdot\text{m}$

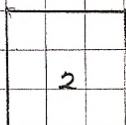
$\vec{r}_{B/C} = (-4, -4, -2) \rightarrow \vec{M}_C = \vec{0}$

c) $\hat{u} = \frac{1}{7}(-6, 2, -3)$

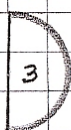
$\vec{M}_{\text{eje}} = -1.96\hat{i} + 0.65\hat{j} - 0.98\hat{k} \text{ N}\cdot\text{m}$



$\bar{x}_1 = 0$; $\bar{y}_1 = -2 \text{ cm}$; $A_1 = 18 \text{ cm}^2$



$\bar{x}_1 = 0$; $\bar{y}_1 = 3 \text{ cm}$; $A_2 = 36 \text{ cm}^2$



$\bar{x}_3 = -(3 - \frac{4}{\pi}) \text{ cm}$; $\bar{y}_3 = 3 \text{ cm}$

$A_3 = \frac{9\pi}{2} \text{ cm}^2$



$\bar{x}_4 = 1 \text{ cm}$; $\bar{y}_4 = 1 \text{ cm}$

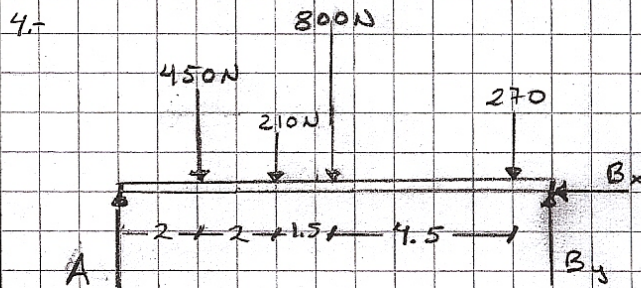
$A_4 = \pi \text{ cm}^2$

$$\sum \bar{x}_i A_i = \bar{x}_1 A_1 + \bar{x}_2 A_2 - \bar{x}_3 A_3 - \bar{x}_4 A_4 = 21.27 \text{ cm}^2$$

$$\sum A_i = A_1 + A_2 - A_3 - A_4 = 36.72 \text{ cm}^2$$

$$\sum \bar{y}_i A_i = \bar{y}_1 A_1 + \bar{y}_2 A_2 - \bar{y}_3 A_3 - \bar{y}_4 A_4 = 32.73 \text{ cm}^2$$

$$\bar{x} = 0.58 \text{ cm} ; \bar{y} = 0.89 \text{ cm}$$



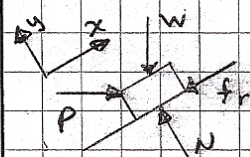
$B_x = 0$, $\sum F_y = A + B_y - 1730 = 0$

$\sum M_A = -2(450) - 4(210) - 5.5(800)$

$-10(270) + 11 B_y = 0$

$A = 926.36 \text{ N}$; $B_y = 803.64 \text{ N}$

5. - Tiende a subir



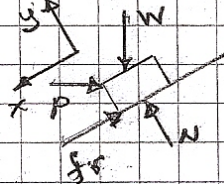
$$\sum F_x = -\frac{1}{2}W + \frac{\sqrt{3}}{2}P - f_r = 0$$

$$\sum F_y = N - \frac{\sqrt{3}}{2}W - \frac{1}{2}P = 0$$

en el limite $f_r = \mu_s N$

$$P = \frac{(\mu_s \sqrt{3} + 1)W}{\sqrt{3} - \mu_s} ; P = 241.73 \text{ N}$$

Tiende a bajar



$$\sum F_x = \frac{1}{2}W - \frac{\sqrt{3}}{2}P - f_r = 0$$

$$\sum F_y = N - \frac{\sqrt{3}}{2}W - \frac{1}{2}P = 0$$

$$P = \frac{(1 - \mu_s \sqrt{3})W}{\sqrt{3} + \mu_s} ; P = 71.52 \text{ N}$$

$$71.52 \text{ N} \leq P \leq 241.73 \text{ N}$$