

“Sistemas de ecuaciones diferenciales lineales usando álgebra lineal”


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Sistemas de ecuaciones diferenciales de primer orden



$$a_2 x''(t) + a_1 x'(t) + a_0 x(t) = F(t)$$

Normalizando

$$x''(t) + \frac{a_1}{a_2} x'(t) + \frac{a_0}{a_2} x(t) = \frac{F(t)}{a_2}$$

$$x'(t) = v(t)$$

$$x''(t) = v'(t)$$


$$x''(t) + \frac{a_1}{a_2} x'(t) + \frac{a_0}{a_2} x(t) = \frac{F(t)}{a_2}$$

$$v'(t) + \frac{a_1}{a_2} v(t) + \frac{a_0}{a_2} x(t) = \frac{F(t)}{a_2}$$

$$v(t) - x'(t) = 0$$

$$v'(t) + \frac{a1}{a2} v(t) + \frac{a0}{a2} x(t) = \frac{F(t)}{a2}$$
$$v(t) - x'(t) = 0$$

Por medio de los operadores diferenciales.

$$\begin{bmatrix} D + \frac{a1}{a2} & \frac{a0}{a2} \\ -1 & D \end{bmatrix} \begin{bmatrix} v(t) \\ x(t) \end{bmatrix} = \begin{bmatrix} \frac{F(t)}{a2} \\ 0 \end{bmatrix}$$

Desacoplando las ecuaciones


$$\begin{pmatrix} D^2 + \frac{a_1}{a_2}D + \frac{a_0}{a_2} \end{pmatrix} \begin{bmatrix} v(t) \\ x(t) \end{bmatrix} = \begin{bmatrix} \frac{F(t)}{a_2} \\ 0 \end{bmatrix}$$

$$\left(D^2 + \frac{a_1}{a_2} D + \frac{a_0}{a_2} \right) x(t) = \begin{bmatrix} D + \frac{a_1}{a_2} & \frac{F(t)}{a_2} \\ -1 & 0 \end{bmatrix}$$

$$\left(D^2 + \frac{a_1}{a_2} D + \frac{a_0}{a_2} \right) x(t) = \frac{F(t)}{a_2}$$

$$\left(D^2 + \frac{a_1}{a_2} D + \frac{a_0}{a_2} \right) v(t) = \begin{bmatrix} \frac{F(t)}{a_2} & \frac{a_0}{a_2} \\ 0 & D \end{bmatrix}$$

$$\left(D^2 + \frac{a_1}{a_2} D + \frac{a_0}{a_2} \right) v(t) = D \begin{bmatrix} \frac{F(t)}{a_2} \end{bmatrix}$$



$$\lambda_{1,2} = -\frac{a_1}{2 a_2} \pm \frac{1}{2 a_2} \sqrt{a_1^2 - 4 a_0 a_2}$$

$$x(t) = C_1 e^{\lambda_1 t} + C_2 e^{\lambda_2 t} + x_p(t)$$

$$v(t) = C_3 e^{\lambda_1 t} + C_4 e^{\lambda_2 t} + v_p(t)$$

Observaciones

- El sistema de ecuaciones se puede descomponer en n ecuaciones diferenciales del mismo orden n de la original.
- Las ecuaciones características y por lo tanto, las raíces y la solución homogénea son similares.
- Al encontrar las soluciones separadas de cada ecuación, aparecen n constantes indeterminadas para cada una de ellas, en total, $2n$ constantes.
- El número total de constantes independientes del sistema es realmente n , por lo que hay que volver a encontrar las relaciones entre las soluciones del sistema de ecuaciones.


$$x'(t)$$

$$= \lambda_1 C_1 e^{\lambda_1 t} + \lambda_2 C_2 e^{\lambda_2 t} \\ + D[xp(t)]$$

$$\lambda_1 C_1 e^{\lambda_1 t} + \lambda_2 C_2 e^{\lambda_2 t} + D[xp(t)] \\ = C_3 e^{\lambda_1 t} + C_4 e^{\lambda_2 t} + vp(t)$$

$$C_3 = \lambda_1 C_1$$

$$C_4 = \lambda_2 C_2$$

Forma matricial de un sistema de ecuaciones

$$v'(t) + \frac{a_1}{a_2} v(t) + \frac{a_0}{a_2} x(t) = \frac{F(t)}{a_2}$$

$$x'(t) - v(t) = 0$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} v'(t) \\ x'(t) \end{bmatrix} + \begin{bmatrix} a_1/a_2 & a_0/a_2 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} v(t) \\ x(t) \end{bmatrix} = \begin{bmatrix} F(t)/a_2 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} v'(t) \\ x'(t) \end{bmatrix} + \begin{bmatrix} a_1/a_2 & a_0/a_2 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} v(t) \\ x(t) \end{bmatrix} = \begin{bmatrix} F(t)/a_2 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} v'(t) \\ x'(t) \end{bmatrix} = \begin{bmatrix} -\frac{a_1}{a_2} & -\frac{a_0}{a_2} \\ 1 & 0 \end{bmatrix} \begin{bmatrix} v(t) \\ x(t) \end{bmatrix} + \begin{bmatrix} F(t)/a_2 \\ 0 \end{bmatrix}$$

$$\bar{q}' = A\bar{q} + \bar{b}$$

$$\bar{q}' = A\bar{q} + \bar{b}$$

$$x' = P x + g(t)$$

$$x' - P x = g(t)$$

$$\mu = e^{-\int P dt}$$

$$\mu(x' - P x) = \mu g(t)$$

$$e^{-\int P dt} (x' - P x) = e^{-\int P dt} g(t)$$

$$e^{-\int P dt} x' - e^{-\int P dt} P x = e^{-\int P dt} g(t)$$

$$d[e^{\int -P dt} x] = e^{\int -P dt} g(t) dt$$

$$e^{-\int P dt} x' - e^{-\int P dt} P x = e^{-\int P dt} g(t)$$

$$d[e^{\int -P dt} x] = e^{\int -P dt} g(t) dt$$

$$e^{-\int P dt} x = \int e^{-\int P dt} g(t) dt + C1$$

$$x = e^{\int P dt} \int e^{-\int P dt} g(t) dt + C1 e^{\int P dt}$$

Valores propios, vectores propios

$$A - \lambda I = \begin{bmatrix} -\frac{a1}{a2} & -\frac{a0}{a2} \\ 1 & 0 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} -\frac{a1}{a2} - \lambda & -\frac{a0}{a2} \\ 1 & -\lambda \end{bmatrix}$$

$$\text{Det}(A - \lambda I) = \left(-\frac{a1}{a2} - \lambda \right) (-\lambda) - \left(-\frac{a0}{a2} \right) = 0$$

$$\lambda^2 + \frac{a1}{a2} \lambda + \frac{a0}{a2} = 0$$

$$(A - \lambda_1 I) \begin{bmatrix} k_{11} \\ k_{21} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -\frac{a_1}{a_2} - \lambda_1 & -\frac{a_0}{a_2} \\ 1 & -\lambda_1 \end{bmatrix} \begin{bmatrix} k_{11} \\ k_{21} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$k_{11} - \lambda_1 k_{21} = 0$$

$$k_{21} = 1$$

$$k_{11} = \lambda_1$$

$$K_1 = \begin{bmatrix} \lambda_1 \\ 1 \end{bmatrix}$$

$$(A - \lambda_2 I) \begin{bmatrix} k_{12} \\ k_{22} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$


$$\begin{bmatrix} -\frac{a_1}{a_2} - \lambda_2 & -\frac{a_0}{a_2} \\ 1 & -\lambda_2 \end{bmatrix} \begin{bmatrix} k_{12} \\ k_{22} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$k_{12} - \lambda_2 k_{22} = 0$$

$$k_{22} = 1$$

$$k_{12} = \lambda_2$$

$$K_2 = \begin{bmatrix} \lambda_2 \\ 1 \end{bmatrix}$$


$$\begin{bmatrix} v(t) \\ x(t) \end{bmatrix} = C1 K1 e^{\lambda_1 t} + C2 K2 e^{\lambda_2 t}$$


$$\begin{bmatrix} v(t) \\ x(t) \end{bmatrix} = C1 \begin{bmatrix} \lambda_1 \\ 1 \end{bmatrix} e^{\lambda_1 t} + C2 \begin{bmatrix} \lambda_2 \\ 1 \end{bmatrix} e^{\lambda_2 t}$$

$$\begin{bmatrix} v(t) \\ x(t) \end{bmatrix} = C1 \begin{bmatrix} \lambda_1 e^{\lambda_1 t} \\ e^{\lambda_1 t} \end{bmatrix} + C2 \begin{bmatrix} \lambda_2 e^{\lambda_2 t} \\ e^{\lambda_2 t} \end{bmatrix}$$

$$X_1 = \begin{bmatrix} \lambda_1 e^{\lambda_1 t} \\ e^{\lambda_1 t} \end{bmatrix} = K_1 e^{\lambda_1 t}$$

$$X_2 = \begin{bmatrix} \lambda_2 e^{\lambda_2 t} \\ e^{\lambda_2 t} \end{bmatrix} = K_2 e^{\lambda_2 t}$$

Wronskiano


$$W(X1, X2) = Det[X1 \ X2]$$

$$W(X1, X2) = Det \begin{bmatrix} \lambda_1 e^{\lambda_1 t} & \lambda_2 e^{\lambda_2 t} \\ e^{\lambda_1 t} & e^{\lambda_2 t} \end{bmatrix}$$

$$W(X1, X2) = \lambda_1 e^{\lambda_1 t} e^{\lambda_2 t} - \lambda_2 e^{\lambda_2 t} e^{\lambda_1 t}$$


$$W(X1, X2) = (\lambda_1 - \lambda_2) e^{(\lambda_1 + \lambda_2)t}$$


$$\Phi(t) = [X1 \ X2]$$

$$\Phi(t) = [K1 e^{\lambda_1 t} \ K2 e^{\lambda_2 t}]$$

$$\Phi(t) = \begin{bmatrix} k11 e^{\lambda_1 t} & k12 e^{\lambda_2 t} \\ k12 e^{\lambda_1 t} & k22 e^{\lambda_2 t} \end{bmatrix}$$

$$\Phi(t) = \begin{bmatrix} k11 & k12 \\ k12 & k22 \end{bmatrix} \begin{bmatrix} e^{\lambda_1 t} \\ e^{\lambda_2 t} \end{bmatrix}$$


$$\begin{bmatrix} v(t) \\ x(t) \end{bmatrix} = \begin{bmatrix} k_{11} e^{\lambda_1 t} & k_{12} e^{\lambda_2 t} \\ k_{12} e^{\lambda_1 t} & k_{22} e^{\lambda_2 t} \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix}$$

$$\overline{qSol} = \Phi(t) \bar{C}$$

$$\bar{q}' = A\bar{q}$$

$$\bar{q} = \Phi(t) \bar{C}$$

$$\bar{q}' = \Phi'(t) \bar{C}$$

$$\bar{q}' = A\bar{q}$$


$$\Phi'(t)\bar{C} = A\Phi(t)\bar{C}$$

$$\Phi'(t)\bar{C} - A\Phi(t)\bar{C} = \bar{0}$$


$$\Phi'(t) - A \Phi(t) = \bar{0}$$

$$\Phi'(t) = A \Phi(t)$$

Valores propios reales diferentes


$$\begin{aligned}3 x'(t) - 3 x(t) - 9 y(t) &= 0 \\-10 x(t) + 2 y'(t) - 6 y(t) &= 0\end{aligned}$$

$$x'(t) = x(t) + 3 y(t)$$

$$y'(t) = 5 x(t) + 3 y(t)$$

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 1 & 3 \\ 5 & 3 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 \\ 5 & 3 \end{bmatrix}$$

$$A - \lambda I = \begin{bmatrix} 1 & 3 \\ 5 & 3 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$$

$$\text{Det}(A - \lambda I) = 0$$

$$\text{Det} \begin{bmatrix} 1 - \lambda & 3 \\ 5 & 3 - \lambda \end{bmatrix} = 0$$

$$(1 - \lambda)(3 - \lambda) - 15 = 0$$

$$\lambda^2 - 4\lambda - 12 = 0$$

$$\lambda_1 = -2$$

$$\lambda_2 = 6$$

$$(A - \lambda_1 I)K_1 = \bar{0}$$

$$\begin{bmatrix} 1 + 2 & 3 \\ 5 & 3 + 2 \end{bmatrix} \begin{bmatrix} k_{11} \\ k_{21} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$k_{11} + k_{21} = 0$$

$$k_{11} = 1$$

$$k_{21} = -1$$

$$K_1 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$(A - \lambda_2 I)K_2 = \bar{0}$$

$$\begin{bmatrix} 1 & -6 & 3 \\ 5 & 3 & -6 \end{bmatrix} \begin{bmatrix} k_{12} \\ k_{22} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$5k_{12} - 3k_{22} = 0$$

$$k_{11} = 3$$

$$k_{21} = 5$$


$$K_2 = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$$

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-2t} + c_2 \begin{bmatrix} 3 \\ 5 \end{bmatrix} e^{6t}$$

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} e^{-2t} \\ -e^{-2t} \end{bmatrix} + c_2 \begin{bmatrix} 3e^{6t} \\ 5e^{6t} \end{bmatrix}$$

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} e^{-2t} & 3e^{6t} \\ -e^{-2t} & 5e^{6t} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

Valores propios reales repetidos



a) Si con un valor repetido n veces se pueden encontrar n vectores linealmente independientes, la solución será la combinación de la misma función con los vectores independientes.

b) si el valor principal de multiplicidad n solamente tiene un vector propio, las soluciones se construyen a partir de nuevos vectores independientes.

$$X'(t) = \begin{bmatrix} 1 & -2 & 2 \\ -2 & 1 & -2 \\ 2 & -2 & 1 \end{bmatrix} X(t)$$

$$X(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & -2 & 2 \\ -2 & 1 & -2 \\ 2 & -2 & 1 \end{bmatrix}$$

$$\text{Det}(A - \lambda I) = 0$$

$$-(-5 + \lambda)(1 + \lambda)^2 = 0$$

$$\begin{bmatrix} 1+1 & -2 & 2 \\ -2 & 1+1 & -2 \\ 2 & -2 & 1+1 \end{bmatrix} \begin{bmatrix} k_{11} \\ k_{21} \\ k_{31} \end{bmatrix} = \bar{0}$$

$$k_{11} - k_{21} + k_{31} = 0$$

$$K1 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$$K2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -5 & -2 & 2 \\ -2 & 1 & -5 & -2 \\ 2 & -2 & 1 & -5 \end{bmatrix} \begin{bmatrix} k_{13} \\ k_{23} \\ k_{33} \end{bmatrix} = \bar{0}$$

$$\begin{aligned} k_{23} + k_{33} &= 0 \\ k_{13} - k_{33} &= 0 \end{aligned} \quad K_3 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

$$X(t) = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} e^{-t} + \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} e^{-t} + \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} e^{5t}$$

$$X1 = K e^{\lambda t}$$

$$X2 = K t e^{\lambda t} + P e^{\lambda t}$$

$$X3 = K \frac{t^2}{2} e^{\lambda t} + P t e^{\lambda t} + Q e^{\lambda t}$$

$$X_2 = K t e^{\lambda t} + P e^{\lambda t}$$

$$X_2'(t) = A X_2(t)$$

$$\begin{aligned} & K \lambda t e^{\lambda t} + K e^{\lambda t} + P \lambda e^{\lambda t} = \\ & = A (K t e^{\lambda t} + P e^{\lambda t}) \end{aligned}$$

$$(A - \lambda I)K = \bar{0}$$

$$(A - \lambda I)P = K$$

$$(A - \lambda I)K = \bar{0}$$

$$(A - \lambda I)P = K$$

$$(A - \lambda I)Q = P$$

$$X_n = K \frac{t^{n-1}}{(n-1)!} e^{\lambda t} + P \frac{t^{n-2}}{(n-2)!} e^{\lambda t} + \dots$$

$$x'(t) = 3x - y - z$$

$$y'(t) = x + y - z$$

$$z'(t) = x - y + z$$

$$X' = \begin{bmatrix} 3 & -1 & -1 \\ 1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix} X$$

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$\lambda_3 = 2$$

$$K1 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$K22 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$K21 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$X_1 = K_1 e^{\lambda_1 t}$$

$$X_2 = K_{21} e^{\lambda_2 t}$$

$$X_3 = K_{22} e^{\lambda_2 t}$$

$$X = C1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} e^t + C2 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} e^{2t} + \\ + C3 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} e^{2t}$$

$$X' = \begin{bmatrix} 4 & 1 & 0 \\ 0 & 4 & 1 \\ 0 & 0 & 4 \end{bmatrix} X$$

$$\lambda_1 = 4$$

$$\lambda_2 = 4$$

$$\lambda_3 = 4$$

$$\begin{bmatrix} 4 & -4 & 1 & 0 \\ 0 & 4 & -4 & 1 \\ 0 & 0 & 4 & -4 \end{bmatrix} \begin{bmatrix} k1 \\ k2 \\ k3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} k1 \\ k2 \\ k3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad K = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & -4 & 1 & 0 \\ 0 & 4 & -4 & 1 \\ 0 & 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} p1 \\ p2 \\ p3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} p1 \\ p2 \\ p3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$p3 = 0,$$

$$p2 = 1,$$

$$p1 = 1$$

$$P = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & -4 & 1 & 0 \\ 0 & 4 & -4 & 1 \\ 0 & 0 & 4 & -4 \end{bmatrix} \begin{bmatrix} q1 \\ q2 \\ q3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} q1 \\ q2 \\ q3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$q3 = 1,$$

$$q2 = 1,$$

$$q1 = 1$$

$$Q = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$X1 = K e^{\lambda_1 t}$$

$$X2 = K t e^{\lambda_2 t} + P e^{\lambda_2 t}$$

$$X3 = K \frac{t^2}{2} e^{\lambda_2 t} + P t e^{\lambda_2 t} + Q e^{\lambda_2 t}$$

$$X = C1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} e^{4t} +$$

$$+ C2 \left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} t + \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right) e^{4t}$$

$$+ C3 \left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \frac{t^2}{2} + \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} t + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right) e^{4t}$$

Valores propios imaginarios conjugados

$$A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

$$(a_{11} - \lambda)(a_{22} - \lambda) - a_{12} a_{21} = 0$$

$$\lambda_{1,2} = \alpha \pm \beta i$$

$$(A - \lambda_1 I)K_1 = \bar{0}$$

$$\begin{bmatrix} a_{11} - \alpha - \beta i & a_{12} \\ a_{21} & a_{22} - \alpha - \beta i \end{bmatrix} \begin{bmatrix} k_{11} \\ k_{21} \end{bmatrix} = \bar{0}$$

$$k_{11}(a_{11} - \alpha - \beta i) + a_{12} k_{21} = 0$$

$$k_{11} = 1,$$

$$k_{21} = \frac{(-a_{11} + \alpha + \beta i)}{a_{12}}$$

$$K_1 = \begin{bmatrix} 1 \\ \frac{(-a_{11} + \alpha + \beta i)}{a_{12}} \end{bmatrix}$$

$$(A - \lambda_2 I)K_2 = \bar{0}$$

$$\begin{bmatrix} a_{11} - \alpha + \beta i & a_{12} \\ a_{21} & a_{22} - \alpha + \beta i \end{bmatrix} \begin{bmatrix} k_{12} \\ k_{22} \end{bmatrix} = \bar{0}$$

$$k_{12}(a_{11} - \alpha + \beta i) + a_{12} k_{22} = 0$$

$$k_{12} = 1$$

$$k_{22} = \frac{(-a_{11} + \alpha - \beta i)}{a_{12}}$$

$$K_2 = \begin{bmatrix} 1 \\ \frac{(-a_{11} + \alpha - \beta i)}{a_{12}} \end{bmatrix}$$

$$K1 = \left[\begin{array}{c} 1 \\ \frac{(-a_{11} + \alpha + \beta i)}{a_{12}} \end{array} \right]$$

$$K2 = \left[\begin{array}{c} 1 \\ \frac{(-a_{11} + \alpha - \beta i)}{a_{12}} \end{array} \right]$$

$$\lambda_1 = \overline{\lambda_2}$$

$$K_1 = \overline{K_2}$$

$$X1 = K1 e^{(\alpha + \beta i)t}$$

$$X2 = K2 e^{(\alpha - \beta i)t} = \overline{K1} e^{\overline{(\alpha + \beta i)t}}$$

$$Xh = C1 X1 + C2 X2$$

$$Xh = C1 K1 e^{(\alpha + \beta i)t} + C2 K2 e^{(\alpha - \beta i)t}$$

$$B1 = \frac{1}{2}(K1 + \overline{K1}), \quad B1 = \text{Re}[K1]$$

$$B2 = \frac{i}{2}(K1 - \overline{K1}), \quad B2 = -\text{Im}[K1]$$

$$X1n = e^{\alpha t} (B1 \cos \beta t + B2 \sin \beta t)$$

$$X2n = e^{\alpha t} (B2 \cos \beta t - B1 \sin \beta t)$$

$$x'(t) = 6x(t) - y(t)$$

$$y'(t) = 5x(t) + 2y(t)$$

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 6 & -1 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

$$A = \begin{bmatrix} 6 & -1 \\ 5 & 2 \end{bmatrix}$$

$$\text{Det} \begin{bmatrix} 6 - \lambda & -1 \\ 5 & 2 - \lambda \end{bmatrix} = 0$$

$$\lambda^2 - 8\lambda + 17 = 0$$

$$\lambda_1 = 4 + i$$

$$\lambda_2 = 4 - i$$

$$\begin{bmatrix} 6 - 4 - i & -1 \\ 5 & 2 - 4 - i \end{bmatrix} \begin{bmatrix} k_{11} \\ k_{21} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$5 k_{11} + (-2 - i)k_{21} = 0$$

$$k_{11} = 2 + i$$

$$k_{21} = 5$$

$$K_1 = \begin{bmatrix} 2 + i \\ 5 \end{bmatrix}$$

$$B_1 = \frac{1}{2}(K_1 + \overline{K_1}), \quad B_1 = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$$

$$B_2 = \frac{i}{2}(K_1 - \overline{K_1}), \quad B_2 = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$X1n = e^{\alpha t} (B1 \cos \beta t + B2 \sin \beta t)$$

$$X2n = e^{\alpha t} (B2 \cos \beta t - B1 \sin \beta t)$$

$$X1n = e^{4t} \left(\begin{bmatrix} 2 \\ 5 \end{bmatrix} \cos \beta t + \begin{bmatrix} -1 \\ 0 \end{bmatrix} \sin \beta t \right)$$

$$X2n = e^{4t} \left(\begin{bmatrix} -1 \\ 0 \end{bmatrix} \cos \beta t - \begin{bmatrix} 2 \\ 5 \end{bmatrix} \sin \beta t \right)$$

Parte no homogénea

$$x' = P x + g(t)$$

$$x = e^{\int P dt} \int e^{-\int P dt} g(t) dt + C_1 e^{\int P dt}$$

$$X' = AX + F(t)$$

$$\Phi(t) = [X_1 \ X_2 \ \dots]$$

$$XSol = \Phi(t) \bar{C}$$

$$X_p = \Phi(t) U(t)$$

$$U(t) = \begin{bmatrix} u_1(t) \\ u_2(t) \\ \vdots \end{bmatrix}$$

$$\Phi(t)U'(t) = F(t)$$

$$U'(t) = \Phi^{-1}(t)F(t)$$

$$U(t) = \int \Phi^{-1}(t)F(t) dt + \bar{C}$$

$$X_{Sol} = \Phi(t) U(t)$$

$$X_{Sol} = X_p + X_h$$

$$x = e^{\int P dt} \int e^{-\int P dt} g(t) dt + C_1 e^{\int P dt}$$

$$XSol = \Phi(t) \bar{C} + \Phi(t) \int \Phi^{-1}(t) F(t) dt$$

$$X' = \begin{bmatrix} 0 & 2 \\ -1 & 3 \end{bmatrix} X + \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^t$$

$$(-\lambda)(3 - \lambda) + 2 = 0$$

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$K1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$K2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Phi(t) = [X1 \ X2]$$

$$\Phi(t) = \begin{bmatrix} 2e^t & 1e^{2t} \\ 1e^t & 1e^{2t} \end{bmatrix}$$

$$\Phi^{-1}(t) = \frac{1}{e^{3t}} \begin{bmatrix} e^{2t} & -e^{2t} \\ -e^t & 2e^t \end{bmatrix}$$

$$U(t) = \int \begin{bmatrix} e^{-t} & -e^{-t} \\ -e^{-2t} & 2e^{-2t} \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^t dt$$

$$= \int \begin{bmatrix} 2 \\ -3e^{-t} \end{bmatrix} dt$$

$$= \begin{bmatrix} 2t \\ 3e^{-t} \end{bmatrix} + \begin{bmatrix} C1 \\ C2 \end{bmatrix}$$

$$XSol = \Phi(t) U(t)$$

$$XSol = \begin{bmatrix} 2e^t & e^{2t} \\ e^t & e^{2t} \end{bmatrix} \begin{bmatrix} 2t \\ 3e^{-t} \end{bmatrix} +$$

$$+ \begin{bmatrix} 2e^t & e^{2t} \\ e^t & e^{2t} \end{bmatrix} \begin{bmatrix} C1 \\ C2 \end{bmatrix}$$

$$XSol = C1 \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^t + C2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{2t} +$$
$$+ \begin{bmatrix} 4te^t + 3e^t \\ 2te^t + 3e^t \end{bmatrix}$$

